## Information Theory Workshop, 2018

$C^{3}$ LES : Codes for Coded Computation that Leverage Stragglers

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## Distributed Matrix-Vector Computation

$$
\begin{gathered}
{\left[\begin{array}{ccccc}
a_{11} & a_{12} & \ldots & \ldots & a_{1 n} \\
a_{21} & a_{22} & \ldots & \ldots & a_{2 n} \\
\ldots & \ldots & \ldots & \ldots & \ldots \\
a_{m 1} & a_{m 2} & \ldots & \ldots & a_{m n}
\end{array}\right] \times\left[\begin{array}{c}
x_{1} \\
x_{2} \\
\ldots \\
\ldots \\
x_{n}
\end{array}\right]=\left[\begin{array}{c}
y_{1} \\
y_{2} \\
\ldots \\
y_{m}
\end{array}\right]} \\
x
\end{gathered}
$$

## Distributed Matrix-Vector Computation



Block rows of A

## Distributed Matrix-Vector Computation

|  | $\ldots$ | $A_{1}$ |
| :--- | :--- | :--- |$\ldots$

Block rows of A


## Distributed Matrix-Vector Computation

|  | $\ldots$ | $A_{1}$ |
| :--- | :--- | :--- |$\ldots$

Block rows of A


Execution time dominated by the speed of the slowest worker.

## Coded Matrix-Vector Multiplication [Lee et al. '16]



Matrix $A$

- Master node calculates $A_{1}+A_{2}$ and sends $A_{1}, A_{2}$, and $A_{1}+A_{2}$ and the vector $x$ to the worker nodes.
- Master node can decode as long as any two worker nodes complete their tasks.


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## Coded Matrix-Vector Multiplication [Lee et al. '16]

$$
\begin{aligned}
& \ldots A_{1} \ldots \\
& \hline \ldots A_{2} \ldots
\end{aligned}
$$

Matrix A


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## Coded Matrix-Vector Multiplication [Lee et al. '16]

- Natural generalization via Reed-Solomon-like approach.

- Master node evaluates $A_{1}+A_{2} z+A_{3} z^{2}$ at $z=1, \ldots, 4$ and sends the evaluations and $x$ to the workers.
- Result can be evaluated by polynomial interpolation at master node as long as at least three workers complete.


## Coded Matrix-Matrix Multiplication [Yu et al. '17]

| $A_{1}^{T}$ |
| :---: |
| $A_{2}^{T}$ |
| Matrix $A^{T}$ |$\underset{$| $B_{1}$ | $B_{2}$ |
| :---: | :---: |$=$| $A_{1}^{T} B_{1}$ | $A_{1}^{T} B_{2}$ |
| :---: | :---: |
| $A_{2}^{T} B_{1}$ | $A_{2}^{T} B_{2}$ |$}{\substack{\text { Matrix } B}}$

## Coded Matrix-Matrix Multiplication [Yu et al. '17]


$A_{1}+A_{2} z$ and $B_{1}+B_{2} z^{2}$ at five different evaluation points.

Only requires scalar multiplication and addition.


## Coded Matrix-Matrix Multiplication

## Coded Matrix-Matrix Multiplication



Worker node i equivalently calculates

$$
A_{1}^{\top} B_{1}+i A_{2}^{\top} B_{1}+i^{2} A_{1}^{\top} B_{2}+i^{3} A_{2}^{\top} B_{2}
$$

Degree sequence chosen carefully ...

## Figures of merit for Coded Computation

- Coding for matrix computations essentially embeds the computation into a Reed-Solomon code.
- Schemes are clearly resilient to the maximum number of node failures.
- Follows directly from RS-like structure.
- Recovery threshold $\tau$ is the minimum number of nodes that need to return their results to the master node for successful decoding.


## Issues with current approaches: Partial Stragglers

## Stragglers are not the same as erasures ...

Unless they are complete node failures

Partial stragglers can be useful ...

## Issues with current approaches: Partial Stragglers



## Issues with current approaches: Partial Stragglers



Approximately 10\% of machines are slow stragglers, but not failures ...

## Issues with current approaches: Partial Stragglers



Modeling the speeds of different stragglers is not easy ...

## Issues with current approaches: Numerical Stability

Vandermonde matrices have very bad condition numbers ...

Condition number of $10^{\ell} \approx$ loss of $\ell$ bits of numerical precision

## Issues with current approaches: Numerical Stability



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Results of interpolating a noisy degree-9 polynomial.

Even at 100 dB, over 5\% error ...

## Issues with current approaches: Numerical Stability



Problematic for machine learning applications ...

Gradient computations are often noisy.

## Issues with curent approaches: Structured matrices

Many practical situations involve sparse matrices.

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Embedding into polynomial of deg- $(k-1)$ increases sparsity level $k$ times.

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Embedding into polynomial of deg- $(k-1)$ increases sparsity level $k$ times.

May even cause computation times to go up [Wang et al. '18] ...

## A Fine Grained Model

We divide matrix A into $\Delta$ blocks, row-wise.
Each worker has a storage capacity of $\gamma=\frac{\ell}{\Delta}$.
Workers sequentially process blocks from top to bottom.

Computation is complete when any $Q$ blocks are processed.

## A Fine Grained Model

We divide matrix A into $\Delta$ blocks, row-wise.
Each worker has a storage capacity of $\gamma=\frac{\ell}{\Delta}$.
Workers sequentially process blocks from top to bottom.

Computation is complete when any $Q$ blocks are processed.

Allows for simple way of capturing different worker speeds!
Ratio $Q / \Delta$ : worst-case computation that needs to take place.

## A Fine Grained Model


$\Delta=3, \gamma=\frac{2}{3}, \mathrm{Q}=4$
Uncoded Solutions

## A Fine Grained Model



$$
\Delta=3, \gamma=\frac{2}{3}, Q=4
$$

## Uncoded Solutions

## A Fine Grained Model



$$
\Delta=3, \gamma=\frac{2}{3}, \mathrm{Q}=3
$$

## Partially Coded Solution

## A Fine Grained Model



$$
\Delta=3, \gamma=\frac{2}{3}, \mathrm{Q}=3
$$

Partially Coded Solution

## Ordering of blocks matters!



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A scheme with $\mathrm{Q}=5$

## Placing the coded blocks first, reduces Q ...



A scheme with $\mathrm{Q}=4$

## Dealing with sparsity \& numerical stability issues

## Constrain the fraction of coded blocks in each worker

Uncoded fraction $\gamma_{u}$

Coded fraction $\gamma_{c}$

## Key Questions under consideration

## For the fine grained model

Bounds on $Q / \Delta$ ?

Achievability schemes for $Q / \Delta$ ?

## Uncoded Scheme



All blocks are uncoded ...

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## Uncoded Scheme: Failure resilience

- Let $r$ be the number of occurrences of each block. Then

$$
n \ell=r \Delta
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## Failure resilience

Consider an $\langle n, \ell, \Delta, r\rangle$-uncoded system. If the system needs to be resilient to $s$ stragglers, then $r \geq s+1$ and $n \gamma=r$.

## Uncoded Scheme: Lower bound on $Q / \Delta$

$$
\text { Example: } Q_{5}=9
$$



- At least one copy of each $A_{j} x$ needs to be obtained by the master node.
- $Q_{j}$ : number of blocks processed in the worst case without processing $A_{j} x$.


## Uncoded Scheme: Lower bound on $Q / \Delta$

$$
Q=1+\max _{j=1, \ldots, \Delta} Q_{j}
$$

Basic Averaging argument yields

$$
Q \geq 1+\frac{\sum_{j=1}^{\Delta} Q_{j}}{\Delta}
$$

## Uncoded Scheme: Lower bound on $Q / \Delta$

Combinatorial argument: Counting $\bar{Q}$ two ways ...

## Uncoded $Q / \Delta$ bound

In an $\langle n, \ell, \Delta, r\rangle$-uncoded system, $Q \geq \max \left(\Delta, \Delta r-\frac{r}{2}(\ell+1)+1\right)$.

## Uncoded Scheme: Matching Constructions Exist

Choosing $\Delta=n$ and placing blocks in a cyclic shift manner ..


Resilient to two failures and meets the $Q / \Delta=2$ bound.

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$$
\Delta=n=5, \ell=3
$$

$$
Q_{1}=9
$$

## Uncoded Scheme: Matching Constructions Exist

Choosing $\Delta=n$ and placing blocks in a cyclic shift manner ..


$$
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Q_{5}=9
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## Uncoded Scheme: Matching Constructions Exist

Choosing $\Delta=n$ and placing blocks in a cyclic shift manner ..

With cyclic construction $Q_{j}$ is the same for each $j$ !

## Mix of uncoded and coded blocks

- Depends on where the coded and uncoded symbols appear in the worker nodes.
- If we expect stragglers to be somewhat infrequent, then it makes sense to put uncoded on top and coded blocks at the bottom. Most of the time decoding complexity will be low.
- Placing coded blocks at the top may reduce the worst-case computation at the expense of decoding complexity.


## Mix of coded and uncoded blocks

- We now assume that each node receives a $\gamma=\gamma_{u}+\gamma_{c}$ fraction of the rows of $A$, where $\gamma_{u}$ and $\gamma_{c}$ correspond to the uncoded and coded parts respectively.
- A $\left\langle n, \ell_{u}, \ell_{c}, \Delta, r_{u}\right\rangle$ system means
- $n$ workers, $\ell$ total blocks in a worker: $\ell_{u}$-uncoded and $\ell_{c}$-coded.
- Each block appears $r_{u}$ times in the uncoded part.


## Coded Blocks at the Bottom: Lower Bound on $\frac{0}{\Delta}$

In the best case each coded block is "useful" to the master node

## Coded blocks at bottom $Q / \Delta$ bound

Consider a $\left\langle n, \ell_{u}, \ell_{c}, \Delta, r_{u}\right\rangle$ system with coded blocks at the bottom. Then,

$$
Q_{c b} \geq \max \left(\Delta, \Delta r_{u}-\frac{r_{u}}{2}\left(\ell_{u}+1\right)+1\right)
$$

. Furthermore, it is resilient to $\left\lfloor\frac{n^{2} \gamma_{c}+n \gamma_{u}-1}{n \gamma_{c}+1}\right\rfloor$ failures.

Lower bound follows from uncoded bound discussed earlier ...

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Lower bound follows from uncoded bound discussed earlier ...

## Coded Blocks at the Bottom: Matching Construction



- We consider the same scenario with $n=5$ and $\gamma=\frac{3}{5}$
- The scheme is resilient to 3 stragglers and $Q_{c b}=8$ if $\ell_{u}=2$.


## Coded Blocks at the Bottom: Matching Construction



## Coded Blocks at the Bottom: Matching Construction



Requires the usage of Cauchy matrices for the coded blocks.

## Cauchy

An $m \times n$ matrix with elements $a_{i j}=\frac{1}{x_{i}-y_{j}}$ where $x_{i}$ and $y_{j}$ are sequences of distinct elements, where $x_{i} \neq y_{j}$ for $1 \leq i \leq m$ and $1 \leq j \leq n$.

## Coded Blocks at the Bottom: Matching Construction



Basic Idea: Place uncoded blocks in a cyclic manner at the top

Cauchy matrices of appropriate dimension at the bottom.

## Coded Blocks at the Top

- A given worker node only processes uncoded blocks after having processed $\ell_{c}$ coded blocks.
- If $x$ coded blocks are processed by workers, then it suffices if any $\Delta-x$ blocks are processed in the uncoded part
- The any $\Delta-x$ fact makes things a lot harder.
- Have lower bounds, but not matching constructions in general ...


## Coded Blocks at the Top



- Consider scenario where $\Delta=n=5$ and $\ell=3$. Here, $\ell_{u}=r_{u}=2$ and $\ell_{c}=1$.
- Once again, lower bound corresponds to case where each coded symbol is useful.


## Coded Blocks at the Top: Lower bound on $\frac{Q}{\Delta}$

- Consider an arbitrary set of $\beta$ worker nodes that process all their blocks and another set of worker nodes that only contribute $x$ coded blocks.
- The total number of coded blocks is $x+\ell_{c} \beta$. Let $\mathcal{A}$ denote the set of distinct uncoded blocks from those $\beta$ workers.

$$
\begin{aligned}
& Q_{c t} \geq x+\ell \beta+1, \text { when } \\
& x+\ell_{c} \beta+|\mathcal{A}|<\Delta .
\end{aligned}
$$

This is because, we do not have enough equations to decode the $\Delta-|\mathcal{A}|$ unknowns.

- Next, we use another averaging argument. We calculate the average size of $\mathcal{A}$ considering all possible $\binom{n}{\beta}$ worker nodes.


## Coded Blocks at the Top

- A lower bound on $Q_{c t}$ can be derived by solving the following optimization problem.

$$
\begin{array}{ll}
\text { maximize } & x+\ell \beta+1 \\
\text { subject to } & \left(x+\ell_{c} \beta\right)<\Delta\left[\frac{\binom{n-r_{u}}{\beta}}{\binom{n}{\beta}}\right]
\end{array}
$$

## Summary of Bound Examples



Q decreases as more coding is introduced.

Matching constructions in two of the cases.

## Questions?

